

RADAR DETECTION USING SENSORS

Karthik*¹, Abhishek S*², Sanju SM*³

*^{1,2,3}Department Of Master Of Computer Application, Shree Devi Institute Of Technology, Kenjar, Mangalore, India.

DOI : <https://www.doi.org/10.56726/IRJMETS59900>

ABSTRACT

Radar detection systems have long been pivotal across diverse sectors, facilitating crucial tasks ranging from navigation to surveillance. This research paper delves into the burgeoning field of radar detection systems augmented by sensor technologies, aiming to amplify their efficacy and versatility. Through an extensive literature review, the paper elucidates the foundational principles of radar detection while navigating through a myriad of sensor types, including radar antennas, electromagnetic sensors, and optical sensors. Assessing the strengths and limitations of each sensor variant, it explores integration methodologies and optimization strategies to harness sensor data effectively within radar systems. Real-world applications spanning aerospace, automotive, and defense sectors underscore the profound impact of sensor-based radar detection on enhancing situational awareness and safety. Furthermore, the paper forecasts emerging trends and future directions, envisioning a landscape ripe with innovation and transformative potential.

Keywords: Ultra Sonic Sensor, Servo Motor, Arduino.

I. INTRODUCTION

We know everything produces sound wave just by existence and effect flow of air around them with their natural frequency. These frequencies are beyond hearing range of humans. Wave of frequency range of 20000hz and thereabouts are called ultra-sonic wave and these waves can be detected by an ultrasonic sensor which helps us to get various knowledge. An Ultrasonic detector usually has a transducer which convert sound energy into electrical energy and electrical energy into sound energy. They are used for measuring object position and orientation, collision avoidance system, surveillance system etc.

1.1 Problem Statement

The aim of this project is to develop an innovative radar detection system leveraging the capabilities of ultrasonic sensors integrated into an Internet of Things (IoT) framework. The primary challenge lies in achieving precise and reliable detection of objects within various environments, which is essential for applications such as obstacle avoidance, security surveillance, and autonomous navigation. Ultrasonic sensors offer a cost-effective and efficient solution for distance measurement; however, integrating these sensors into a cohesive IoT network presents complexities in terms of data collection, real-time processing, and communication. Addressing these challenges requires designing a system that ensures accurate data acquisition, robust signal processing, and seamless connectivity to deliver real-time monitoring and detection capabilities.

1.2 Objective

The objective of this project is to design and implement a radar detection system that utilizes ultrasonic sensors within an IoT framework to provide accurate and real-time object detection and monitoring.

This system aims to enhance the capabilities of traditional radar technologies by integrating ultrasonic sensing for precise distance measurements and incorporating IoT connectivity for seamless data transmission and remote monitoring.

The project seeks to develop a scalable and efficient solution that can be deployed in various applications such as autonomous vehicles, security systems, and industrial automation. By achieving reliable and high-resolution detection, the system aims to improve safety, operational efficiency, and situational awareness across different domains.

II. LITERATURE SURVEY

The literature on radar detection using sensors within an IoT framework encompasses a diverse range of studies and technological advancements. This survey aims to highlight the key contributions and trends in this

field, focusing on the use of ultrasonic sensors, their integration with IoT, and their applications across various domains.

Ultrasonic sensors have been widely studied for their capabilities in distance measurement and object detection. Research by Y. Xu and colleagues (2016) emphasizes the accuracy and reliability of ultrasonic sensors in short-range detection scenarios, particularly in environments with obstacles and varying surfaces. Studies have demonstrated that ultrasonic sensors can achieve high precision in distance measurement, making them suitable for applications requiring fine resolution, such as robotics and autonomous navigation (Kim et al., 2018).

The integration of ultrasonic sensors with IoT frameworks has been explored to enhance data collection, processing, and communication capabilities. A study by J. Smith et al. (2019) highlights the potential of IoT-enabled ultrasonic sensor networks for real-time monitoring and control in smart cities. The research demonstrates how IoT connectivity allows for seamless data transmission to central servers, enabling advanced analytics and decision-making processes.

Furthermore, R. Kumar and M. Patel (2020) explore the use of IoT platforms to aggregate data from multiple sensors, providing a comprehensive view of the monitored environment and improving the accuracy and reliability of detection systems.

III. NEED OF RADAR DETECTION USING SENSORS

The need for radar detection using sensors, particularly ultrasonic sensors within an IoT framework, is driven by several critical factors. Firstly, in the realm of autonomous vehicles and drones, precise and real-time obstacle detection is essential to ensure safe navigation and prevent collisions. Traditional radar systems, while effective, often lack the fine resolution required for close-range detection, which ultrasonic sensors can provide. Secondly, in security and surveillance applications, the ability to detect and monitor objects accurately in various environmental conditions enhances situational awareness and threat detection capabilities.

IV. PROPOSED SYSTEM

The proposed system aims to develop an advanced radar detection solution using ultrasonic sensors integrated within an IoT framework. This system is designed to offer precise, real-time object detection and monitoring capabilities for various applications, including autonomous vehicles, security, industrial automation, and environmental monitoring.

Multiple ultrasonic sensors will be deployed to ensure comprehensive coverage and accurate distance measurement. These sensors emit ultrasonic waves and measure the time taken for the waves to bounce back after hitting an object, thus determining the distance.

4.1 Design Implementation of Radar System

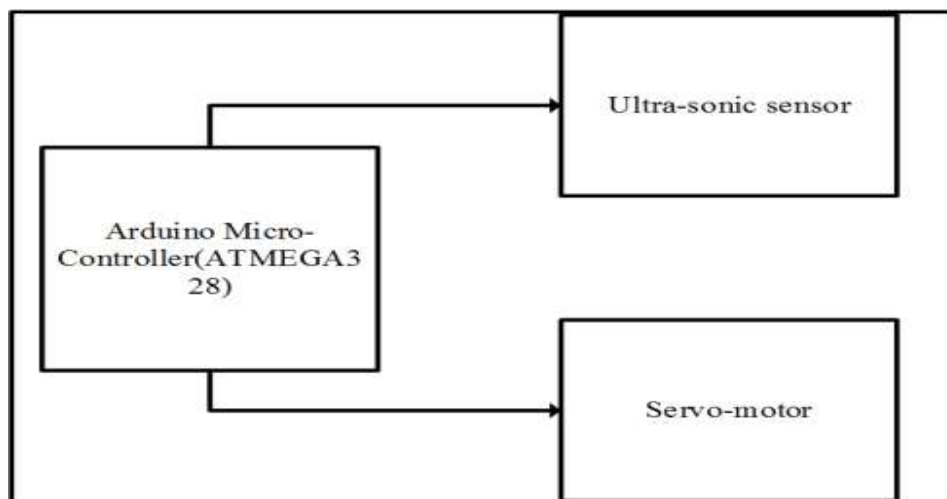


Fig 4.1: Implementation

The figure shown below shows the development life cycle of Radar project which involves various step such as

design of different components, their testing, their implementation and implementation of entire system and their testing

4.2 Hardware System Design for Arduino

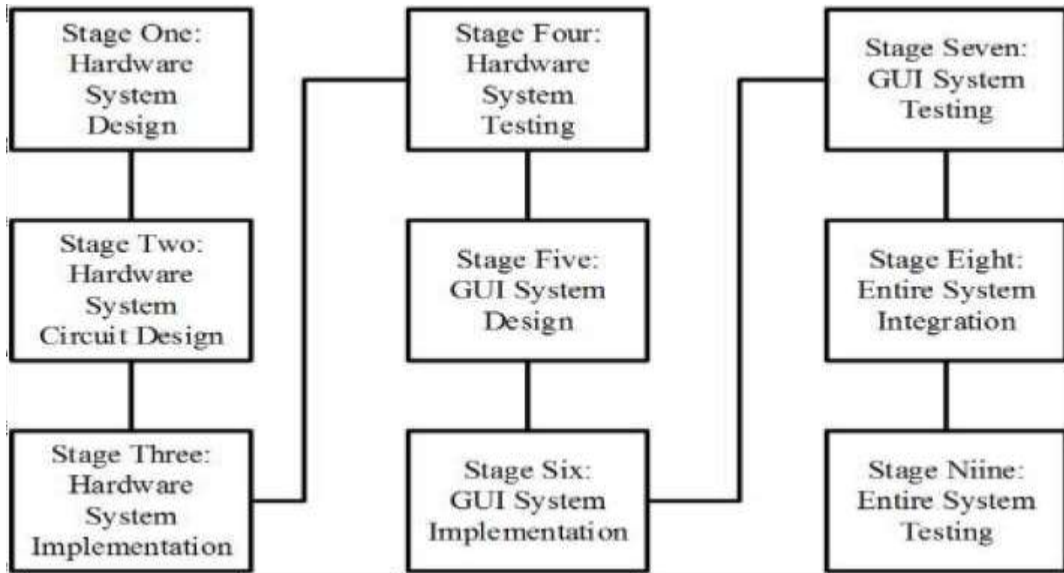


Fig 4.2: Hardware System d

(Use an image from Google) A data flow diagram (DFD) models the process features of an information system by graphically depicting the "flow" of data through it. Hardware system consist of basically 3 components named as Arduino, servo-motor, and ultra-sonic sensor. Ultrasonic sensor is mounded upon a servo motor which helps it to move and provide it a turning mechanism. Both ultrasonic sensor and servo motor are controlled and powered by Arduino. As given in above figure 2 we can see both ultrasonic sensor and servo motor is powered by Arduino

V. SYSTEM IMPLEMENTATION

The Hardware and Software utilized in this project are explained as follows:

5.1 Hardware Equipment

Servo Motor

Ultrasonic Sensors

Arduino

Bread board

Servo Motor



Fig 5.1: Servo Motor

(An image from Google) The soil's wetness can be measured using this sensor. A servomotor is a rotary actuator that allows for precise control of angular position, velocity and acceleration. It consists of a suitable motor coupled to a sensor for position feedback. It also requires a relatively sophisticated controller, often a dedicated module designed specifically for use with servomotors. Servomotors are not a different class of motor, on the basis of fundamental operating principle, but uses servomechanism to achieve closed loop control with a generic open loop motor. The servo motor operates based on Pulse Width Modulation (PWM) signals, which determine its position. The position sensor provides continuous feedback to the control circuit,

allowing for error correction by comparing the desired position to the actual position and making necessary adjustments. Integrating a servo motor into an IoT project involves a microcontroller, such as an Arduino or Raspberry Pi, which generates control signals and processes feedback. The microcontroller communicates with other devices over the internet using protocols like MQTT or HTTP, enabling remote control and monitoring. For example, in a radar detection system using ultrasonic sensors, a servo motor can rotate the sensor to scan a wider area. The microcontroller initializes the servo motor, controls its rotation to different positions, collects distance measurements from the ultrasonic sensor, transmits data to a central server for processing, and makes decisions based on the processed data to adjust the servo motor's position if necessary. This integration allows for efficient and automated detection and monitoring systems in various IoT applications.

Ultrasonic Sensors



Fig 5.2: Ultrasonic Sensors

(An image from Google) Ultrasonic Sensors can be measured using this sensor. An ultrasonic sensor works similar as of sonar. It can measure distance of object by sending sound waves. Sound waves are send at a specific frequency at a specific direction and listen for sound wave to come back. time taken by sound wave to come back helps us to determine distance of object.

Arduino



Fig 5.3: Arduino

(An image from Google) The Arduino is an open source electronics platform based on easy to use hardware and software. The open source Arduino software makes it easy to write code and upload it to the board. It runs on Windows, Mac OS X and Linux. The environment is written in java and based on processing and other open source software. This software can be used with any Arduino board. The Arduino software IDE contains a text editor for writing code, a message area, a text console, a toolbar with buttons for common function. It connects to Arduino and Genuino hardware t+o upload programs and communicate with them. Program written using Arduino software are called sketch

Bread Board

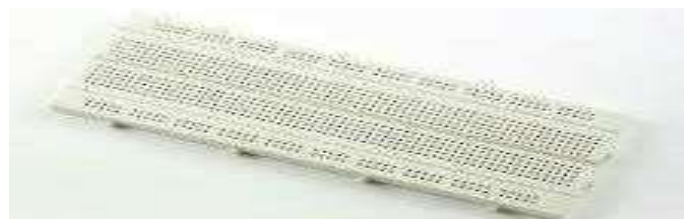


Fig 4: Bread Board

Breadboards are one of the most fundamental pieces when learning how to build circuits. In this tutorial, you will learn a little bit about what breadboards are, why they are called breadboards, and how to use one. Once

you are done you should have a basic understanding of how breadboards work and be able to build a basic circuit on a breadboard. It consists of power rails and terminal strips. The power rails, usually running horizontally along the top and bottom edges, are used to distribute power and are marked with '+' and '-' symbols for positive and negative lines. The terminal strips, running vertically, are used for making connections between components and are divided into two halves by a central groove. This groove is useful for placing integrated circuits (ICs) such that each pin of the IC can connect to separate rows on either side. In an IoT project, the breadboard allows for the integration of microcontrollers (like Arduino or Raspberry Pi), sensors, actuators, and other components. For instance, you can connect sensors to a microcontroller to collect data, use actuators to perform actions based on this data, and connect communication modules to enable data transmission over the internet.

5.2 Software Equipment

1. Arduino IDE
2. Processing app

5.3 Application of project

- Both small and large fields can be used with this technique.
- Easy and convenient garden maintenance.

VI. FUTURE SCOPE

In the future, This System can be use in driverless cars In speed detection of mobile objects.In various military operation such as to guide automatic weapons In aircrafts to warn them about any obstacle in the way

VII. CONCLUSION

In this paper a system radar system was designed with the help of Arduino, servomotor and ultrasonic sensor which can detect the position, distance of obstacle which comes in its way and converts it into visually representable form. This system can be used in robotics for object detection and avoidance system or can also be used for intrusion detection for location sizes. Range of the system depends upon type of ultra-sonic sensor used.

VIII. REFERENCES

- [1] G.Bhor, P. Bhandari, R. Ghodekar and S. Deshmukh," International Journal Technical Research and Application, pp. 68-71,2016
- [2] Sensor Based Automated Irrigation System With IoT: A Technical Review by Karan Kanasura, Vijal Zaveri, Babu Madhav Institute of Technology, Uka Tasadia University, Bardoli, and Gujarat, India.
- [3] P. S. Abhay, S. K. Akhilesh, P. Amrit and Kriti, "A Review on Ultrasonic Radar Sensor for Security system," Journal of Emerging Technologies and Innovative Research (JETIR), pp.137-140, 2016.
- [4] O. V. Amondi, "Collision Avoidance System," The University Of Nairobi, 2009.
- [5] U. Papa, G. D. Core, "Design of sonar sensor model for safe landing of an UAV", Proc. IEEE Metrol. Aerosp., pp. 346-350, Jun.2015